



On an electrodynamic origin of quantum fluctuations

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Abstract We use the Liénard–Wiechert potential to show that very violent fluctuations are experienced by an electromagnetic charged extended particle when it is perturbed from its rest state. The feedback interaction of Coulombian and radiative fields among different charged parts of the particle makes uniform motion unstable. Then, we show that radiative fields and radiation reaction produce dissipative and anti-damping effects, triggering a self-oscillation. Finally, we compute the self-potential, which in addition to rest and kinetic energy, gives rise to a new contribution that shares features with the quantum potential. We suggest that this contribution to self-energy produces a symmetry breaking of the Lorentz group, bridging classical electromagnetism and quantum mechanics.

Keywords Nonlinear dynamics · Self-oscillation · Quantum fluctuations · Electrodynamics · Relativity

1 Introduction

It was shown in the mid-sixties that a dynamical theory of quantum mechanics can be provided based on a process of conservative diffusion [1]. The theory of stochastic mechanics is a monumental mathematical

achievement that has been carefully and slowly carried out along two decades with the best of the rigors and mathematical intuition [2]. However, as far as the authors are concerned, the grandeur of this theoretical effort is that it proposes a kinematic description of the dynamics of quantum particles, based on the theory of stochastic processes [3]. Just as Bohmian mechanics [4,5], it tries to offer a geometrical picture of the trajectory of a quantum particle, which would be so very welcomed by many physicists. In the end, establishing a link between dynamical forces and kinematics is at the core of Newton’s revolutionary work [6].

Perhaps, the absence of geometrical intuition in this traditional sense, during the development of the quantum mechanical formalism, has hindered the understanding of the underlying physical mechanism that leads to quantum fluctuations. In turn, it has condemned the physicist to a systematic titanic effort of mathematical engineering, designing ever-increasing complicated theoretical frameworks. Despite providing a very refined explanation of many experimental data, which is the main purpose of any physical theory, needless to say, these frameworks entail a certain degree of obscurantism and a lack of understanding. Concerning comprehension only, quantum mechanics constitutes a paradigm of these kinds of paradoxical theories, which imply that the more time that it is dedicated to their study, the less clear that the physical picture of nature becomes. As it has been pointed out by Bohm, this might be a consequence of renouncing to models in

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which all physical objects are unambiguously related to mathematical concepts [4].

On the contrary, hydrodynamical experimental models that serve as analogies to quantum mechanical systems have been developed recently, which allow us to clearly visualize how the dynamics of a possible quantum particle might be [7,8]. These experimental contemporary models share many features with the mechanics of quantum particles [9,10] and, fortunately, they are based on firmly established and understandable principles of nonlinear dynamical oscillatory systems and chaos theory [11,12]. As it is well accepted, these conceptual frameworks have shaken the grounds of the physical consciousness of many scientists by showing the tremendous complexity of the dynamical motion of rather simple classical mechanical systems, and not so simple as well [12]. Doubtlessly, the development of computation has proven to be a fundamental tool in this regard, serving as a microscope to the modern physicist, which allows him to unveil the complex patterns and fractal structures that explain the hidden regularities of chaotic motion [13,14]. Thus, even if we can not experimentally trace a particle's path because we perturb its dynamics by the mere act of looking at it, we can always use our powerful computers to simulate their dynamics.

In the final pages of Nelson's work, it is seductively suggested that a theory of quantum mechanics based on classical fields should not be disregarded, as was originally the purpose of Albert Einstein [2]. This aim of providing quantum mechanics with a kinematic description, together with the desire of showing the unjustified belief of electrodynamic fields as a merely dissipative force on sources of charge, and not as an exciting self-force as well, are the two core reasons that have spurred the authors to pursue the present goal. By using a toy model and rather simple mathematics, we show as a main result in what follows that a finite-sized charged accelerated body always carries a vibrating field with it, what can convert this particle into a stable limit cycle [15] oscillator by virtue of self-interactions. This implies that the rest state of this charged particle can be unstable, and that stillness (or uniform motion) might not the default state of matter, but also accelerated oscillatory dynamics. We close this work by deriving an analytical expression of the self-potential. For this purpose, we only need to assume that inertia is of purely electromagnetic origin. As it will be demonstrated, the first-order terms of this self-potential contain the relativistic energy (the rest and

the kinetic energy) of the electrodynamic body, while terms of higher order can be related to a new function, that can be correlated to the quantum potential. In this manner, we hope to provide a better understanding of quantum motion or, at least, to pave the way towards such an understanding.

2 The self-force

We begin with the Liénard–Wiechert potential [16,17] for a body formed by two charged point particles attached to a neutral rod that move transversally along the x -axis. From a mathematical point of view, we can disregard the rod and simply assume a rigid density of charge. In general, any motion with a transversal field component suffices to derive the main conclusions of this work. However, to avoid dealing with the rotation of the dumbbell, we restrict to a one-dimensional translational motion. This allows to keep mathematics as simple as possible, since the Liénard–Wiechert potential is retarded in time, and this non-conservative character of electrodynamics makes the computations very entangled. This elementary model was wisely designed in previous works to derive from first principles the Lorentz–Abraham force [18,19] and also to study a possible electromagnetic origin of inertia [20,21]. It is a toy model of an electron, represented as an extended electrodynamic body with an approximate size d , as shown in Fig. 1. Among the aforementioned virtues, we also find that some properties resulting from considering more complex geometries (spherical, for example) of a particle, can be derived by superposition [21]. We shall use this elementary model all along our exposition, which is more than sufficient to illustrate the fundamental mechanism that leads to electrodynamic fluctuations.

As we can see in Fig. 1, the first particle can emit a perturbation at the retarded time t_r , which affects the other particle at a later time t , after advancing some distance l . In other words, an extended body can affect itself at different times, since the field perturbations have to travel from some parts of the body to the others. This sort of interaction is traditionally known as a self-interaction in the literature [20] and, as can be seen ahead, for any charged particle, it produces an excitatory force, together with a recoil force and an elastic restoring force as well. The complete Liénard–Wiechert potential permits to write the electric field created by the first particle at the point of the second as

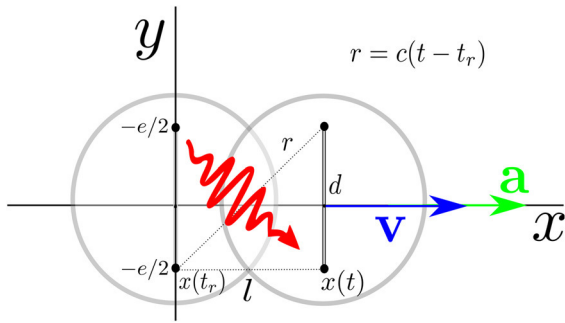


Fig. 1 A model for an electrodynamic body. An extended electron, modeled as a rod joining two point charged particles (black dots) at a fixed distance d . The particle is shown at the retarded time t_r , and at a some later time t . During this time interval, the corpuscle accelerates in the x -axis (green vector) acquiring certain speed (blue vector) and advancing some distance l in such direction. As we can see, the particle in the upper part emits a field perturbation at the retarded time (red photon), and this perturbation reaches the second particle at the opposite part of the dumbbell at a later time (and vice versa)

$$E_1 = \frac{q}{8\pi\epsilon_0} \frac{r}{(r \cdot u)^3} \left(u(1 - \beta^2) + \frac{1}{c^2} r \times (u \times a) \right), \quad (1)$$

where we have now defined the vector $u = \hat{r} - \beta$, with the relative position between particles $r(t_r)$, their velocity $\beta(t_r) = v(t_r)/c$ and their acceleration $a(t_r)$ depending on the retarded time $t_r = t - r/c$. The retarded time appears due to the limited speed at which electromagnetic field perturbations travel in spacetime, according to Maxwell's equations [22]. This restriction imposes the constraint

$$r = c(t - t_r), \quad (2)$$

which assigns a particular time in the past from which the signals coming from one particle of the dumbbell affect the remaining particle. As we shall see, the fact that dynamical systems under electrodynamic interactions are time-delayed (*i.e.* the non-Markovian character of electrodynamics), is at the basis of the whole mechanism. Now we follow the picture in Fig. 1 and write the position, the velocity and the acceleration vectors as $r = l\hat{x} + d\hat{y}$, $\beta = v/c\hat{x}$ and $a = a\hat{x}$, respectively, where the distance $l = x(t) - x(t_r)$ between the present position of the particle and the position at the retarded time has been introduced. Using these relations, the vector u can be computed immediately as

$$u = \frac{(l - r\beta)\hat{x} + d\hat{y}}{r}, \quad (3)$$

which, in turn, allows to write the inner product $r \cdot u = r - l\beta$, by virtue of the Pythagoras' theorem $r^2 = (x(t) - x(t_r))^2 + d^2$. Concerning the radiative fields, we can express the triple cross-product as $r \times (ru \times a) = -d^2a\hat{x} + dal\hat{y}$. We now compute the net self-force on the particle's centre of mass as

$$F_{\text{self}} = \frac{q}{2}(E_1 + E_2) = qE_{1x}\hat{x}, \quad (4)$$

where E_2 is the force of the second particle on the first. Note that we have assumed that all the forces on the y -axis cancel, because we have simplified the model by using a rigid charge density to keep the distance of the charges fixed. This includes repulsive electric forces and also magnetic attractive forces as well. Therefore, in the present section, we do not cover the much more complicated problem of the particle's stability, which is discussed in the last section of the present work. Such a problem is of the greatest importance, led to the introduction of Poincaré's stresses in the past [23] and, among other reasons (*e.g.* atomic collapse), to the rejection of classical electrodynamics as a fundamental theory [24]. If preferred, from a theoretical point of view, the reader can consider that the two point particles of our model are kept at a fixed distance by means of some balancing external electromagnetic field oriented along the y -axis.

Now, we replace the value of the charge with the charge of the electron $q = -e$ to finally arrive at the mathematical expression describing the self-force of the particle, which is written as

$$F_{\text{self}} = \frac{e^2}{8\pi\epsilon_0} \frac{1}{(r - l\beta)^3} \times \left((l - r\beta)(1 - \beta^2) - \frac{d^2}{c^2} a \right) \hat{x}. \quad (5)$$

3 The equation of motion

We are now committed to writing down Newton's second law in the non-relativistic limit $F_{\text{self}} = ma$ and redefine the mass of the particle since, as we show right ahead, the electrostatic internal interactions add a term to the inertial content of the particle. The main purpose of the following lines is to expand in series the self-force to show its different contributions to the equation of motion. The two most resounding terms are the Lorentz–Abraham force and the force of inertia. However, we draw attention to other relevant nonlinear terms, which are of fundamental importance. These

217 expansions will enable a discussion about the electro-
 218 magnetic origin of mass and, based on such a line of
 219 reasoning, we shall derive the appropriate and precise
 220 equation of motion.

221 As it has been shown in previous works [20,21], it
 222 is possible to express l as a function of r by means of
 223 the series expansion

$$224 \quad l = x\left(t_r + \frac{r}{c}\right) - x(t_r) \\
 225 \quad = \beta r + \frac{a}{2c^2}r^2 + \frac{\dot{a}}{6c^3}r^3 + \frac{\ddot{a}}{24c^4}r^4 + \dots \quad (6)$$

226 This trick of approximating magnitudes presenting
 227 delay differences employing a Taylor series has been
 228 used sometimes in the study of delayed systems along
 229 history [25]. We recall that this simplification is not a
 230 minor issue, since by truncating this expansion we are
 231 replacing a system with memory by a Markovian one.
 232 Nevertheless, the reader must be aware that delayed
 233 systems are infinite-dimensional. As we show below,
 234 any truncation of the previous equation is mistaken
 235 since, even though the time-delay r/c is small, the terms
 236 in the acceleration, the jerk, and so on, are not of order
 237 zero in such factor.

238 As shown in the Appendix, together with Eq. (2), the
 239 previous expansion allows to express the corpuscle's
 240 size in terms of the time-delay by means of the series

$$241 \quad d = r - \frac{a}{2c^2}\beta r^2 - \left(\frac{a^2}{8c^4} + \beta\frac{\dot{a}}{6c^3}\right)r^3 + \dots \quad (7)$$

242 This Taylor series can be inverted to compute the expansion
 243 of r in terms of d , which can be written to first order
 244 in β as

$$245 \quad r = d + \frac{a}{2c^2}\beta d^2 + \left(\frac{a^2}{8c^4} + \beta\frac{\dot{a}}{6c^3}\right)d^3 + \dots \quad (8)$$

246 Finally, by inserting Eq. (8) in the previous Eq. (6) and
 247 then both equations in Eq. (5), with the aid of Newton's
 248 second law, we compute, to first order in β , the identity

$$249 \quad \left(m + \frac{e^2}{16\pi\epsilon_0 c^2 d}\right)\mathbf{a} = \frac{e^2}{8\pi\epsilon_0} \left(\frac{1}{2c^5}a^2\mathbf{v} \right. \\
 250 \quad \left. + \frac{5d}{16c^6}a^2\mathbf{a} + \frac{1}{6c^3}\dot{\mathbf{a}} + \frac{d}{24c^4}\ddot{\mathbf{a}} + \dots\right), \quad (9)$$

251 after a great deal of algebra. These computations are
 252 enormously simplified by means of modern software
 253 for symbolic computation [26].

254 We notice that the Lorentz–Abraham force has
 255 appeared in the third term of the right-hand side of
 256 this last equation, together with a few other linear and

257 nonlinear terms. Interestingly, we recall that the term
 258 of inertia dominates all other terms for small speeds
 259 and accelerations. We can truncate this equation up to
 260 the jerk term $\dot{\mathbf{a}}$, disregarding its nonlinearity and also
 261 derivatives of a higher order. We can also define the
 262 renormalized mass of the electron as

$$263 \quad m_e = m + \frac{e^2}{16\pi\epsilon_0 c^2 d}, \quad (10)$$

264 and recall the relation between the electron's charge
 265 and Planck's constant by means of the fine structure
 266 constant

$$267 \quad \hbar\alpha c = \frac{e^2}{4\pi\epsilon_0}, \quad (11)$$

268 according to Sommerfeld's equation [27]. Then, we get
 269 the approximated solution

$$270 \quad \ddot{\boldsymbol{\beta}} - \frac{12m_e c^2}{\hbar\alpha} \dot{\boldsymbol{\beta}} \left(1 - \frac{5\hbar\alpha d}{32m_e c^3} \dot{\boldsymbol{\beta}}^2\right) \\
 271 \quad + \frac{3a^2}{c^2} \boldsymbol{\beta} + \dots = 0, \quad (12)$$

272 which reminds of the equation of a nonlinear oscillator.

273 Thus, we see that the term of inertia, which is the linear
 274 term in the acceleration and which dominates when
 275 the particle is perturbed from rest, acts as an antidamp-
 276 ing. This term is due to radiation fields and is responsible
 277 for the amplification of fluctuations. This fact does
 278 not contradict Newton's third law, since it is the addition
 279 of matter and radiation momentum that must be
 280 conserved as a whole. In other words, the particle can
 281 propel itself for a finite time by taking energy from
 282 its "own" field. However, the nonlinear cubic term in
 283 $\dot{\boldsymbol{\beta}}$ in Eq. (12), which has the opposite sign, limits the
 284 growth of the fluctuations. When the acceleration sur-
 285 passes a certain critical value, the radiation reaction
 286 and the radiative fields do not act in phase anymore,
 287 and the fluctuations are damped away. Therefore, the
 288 pathological attributes that have been predicated of this
 289 marvelous recoil force [21] are unjustified and arise as a
 290 consequence of disregarding nonlinearities, which are
 291 responsible for the system's stabilization and, as we
 292 shall demonstrate, its self-oscillatory dynamics.

293 Importantly, at this point we notice that, if we assume
 294 that the inertia of the electron has an exclusive electro-
 295 magnetic origin and recall that the dumbbell is neutral
 296 ($m = 0$) or absent, all the mass must come from the
 297 charged points. Then, using Eqs. (10) and (11) we can
 298 write the mass as

$$299 \quad m_e = \frac{\hbar\alpha}{4dc}, \quad (13)$$

Author Proof

300 which was obtained in previous works [20] and gives
 301 an approximate radius of the particle $r_e = d/2 =$
 302 $3.52 \times 10^{-16} \text{m}$. Except for a factor of eight due to
 303 the dumbbell's geometry, this value corresponds to the
 304 classical radius of the electron. In this manner, we
 305 do not need to introduce spurious elements (artificial
 306 mechanical inertia) in the theory of electromagnetism,
 307 and simply use the D'Alembert's principle instead of
 308 Newton's second law [28]. If desired, and to extol New-
 309 ton's intuition, the second law of classical mechanics
 310 would be a conclusion of electromagnetism, which is
 311 the most fundamental of classical theories. What is
 312 amazing is that Newton was capable of figuring it out
 313 without any knowledge of electrodynamics. However,
 314 this wonderment partly fades out if we bear in mind
 315 the unavoidable corollary. For if mass is of electromag-
 316 netic origin, the gravitational field must be a residual
 317 electromagnetic field. If we are willing to accept these
 318 two inextricable facts, inertia would just be an internal
 319 resistance or self-induction force produced by the field
 320 perturbations to the motion of the charged body, when
 321 an external field is applied. We tackle more deeply this
 322 issue in the colophon of this work.

339 tions it is straightforward to derive a second-order poly-
 340 nomial in r , which is solved yielding

$$r = \gamma d \sqrt{1 + \gamma^6 \dot{\beta}^2 \left(\frac{d}{c}\right)^2 + \gamma^4 c \beta \dot{\beta} \left(\frac{d}{c}\right)^2}, \quad (15)$$

342 where the Lorentz factor $\gamma = (1 - \beta^2)^{-1/2}$ has been
 343 introduced and the kinematic variables are evaluated at
 344 the retarded time. Note that, contrary to the previous
 345 Eq. (8), this expression is exact and has the virtue of
 346 suggesting that any consistent power series expansion
 347 of r should be carried out in terms of the factor d/c .
 348 We also notice that, by virtue of this equation, the delay
 349 becomes dependent on the speed and the acceleration of
 350 the particle. As the corpuscle speeds up, the self-signals
 351 come from earlier times in the past. In other words, the
 352 light cone of the corpuscle is dynamically evolving, and
 353 this evolution selects different signals coming from the
 354 past.

355 Finally, the insertion of this relation into the equation
 356 $r^2 = l^2 + d^2$ leads to the obtainment of l as a function
 357 of β and $\dot{\beta}$ in a closed form. Again, this avoids the use
 358 of an infinite number of derivatives. The final result can
 359 be written as

$$l = \sqrt{\gamma^2 c^2 \beta^2 \left(\frac{d}{c}\right)^2 + \gamma^8 c^2 \dot{\beta}^2 (1 + \beta^2) \left(\frac{d}{c}\right)^4 + 2c^2 \gamma^5 \beta \dot{\beta} \left(\frac{d}{c}\right)^3 \sqrt{1 + \gamma^6 \dot{\beta}^2 \left(\frac{d}{c}\right)^2}}. \quad (16)$$

361 In summary, we believe that it is more appropri-
 362 ate to simply consider Newton's second law as a static
 363 problem $\mathbf{F}_{\text{ext}} + \mathbf{F}_{\text{self}} = 0$. In our case, we simply
 364 have $\mathbf{F}_{\text{self}} = 0$. This way of posing the problem can be
 365 regarded as computing the geodesic equation of motion
 366 of the particle, as it occurs, for example, in the theory
 367 of general relativity. The resulting equation of motion
 368 reads

$$\left(1 - \frac{v^2(t_r)}{c^2}\right) \left(x(t) - x(t_r) - \frac{r}{c} v(t_r)\right) - \frac{d^2}{c^2} a(t_r) = 0, \quad (14)$$

369 where we recall that for $v = c$ the first term vanishes,
 370 not allowing the particle to overcome the speed of light.

371 We now derive two relations that shall prove of great
 372 assistance in forthcoming sections to compute exact
 373 results. For this purpose, we use again the Pythagoras'
 374 theorem $r^2 = (x(t) - x(t_r))^2 + d^2$ and the equality
 375 appearing in Eq. (14). By combining these two equa-

361 These two Eqs. (15) and (16) will allow us to derive
 362 exact analytical results in a fully relativistic manner,
 363 specially concerning the self-potential.

364 4 The instability of rest

365 Even though we shall prove a more general statement in
 366 Sect. 5, we believe that the fact that oscillatory dynam-
 367 ics can be the default state of matter, instead of a station-
 368 ary state, is of paramount importance. In turn, this study
 369 provides a double-check of the results presented in such
 370 a section. Therefore, we independently study the stabil-
 371 ity of the rest state of the particle in the following lines.
 372 Our goal is to show that the rest state is unstable and to
 373 identify the magnitude that leads to the amplification of
 374 fluctuations. For this purpose, we begin with the expan-
 375 sion appearing in Eqs. (6) and (8), and replace them in
 376 Eq. (14), neglecting all the nonlinear terms. Such terms
 377 can be disregarded since the rest state is represented by

378 v and all its higher derivatives are equal to zero. Thus,
 379 when slightly perturbing the rest state of the charged
 380 particle, we only need to retain linear contributions. The
 381 resulting infinite-dimensional differential equation is

$$382 \quad -\frac{1}{2c^2d} \mathbf{a} + \frac{1}{6c^3} \dot{\mathbf{a}} + \frac{d}{24c^4} \ddot{\mathbf{a}} + \frac{d^2}{120c^5} \dddot{\mathbf{a}} + \dots = 0. \quad (17)$$

384 This equation can be more clearly written as a Lau-
 385 rent series in the factor d/c , as previously suggested.
 386 We obtain the result

$$387 \quad -\frac{1}{2} \frac{c}{d} \mathbf{a} + \frac{1}{6} \dot{\mathbf{a}} + \frac{1}{24} \frac{d}{c} \ddot{\mathbf{a}} + \frac{1}{120} \frac{d^2}{c^2} \dddot{\mathbf{a}} + \dots = 0, \quad (18)$$

388 which can be generally expressed as

$$389 \quad -\frac{1}{2} \mathbf{a} + \sum_{n=1}^{\infty} \frac{1}{(n+2)!} \frac{d^n \mathbf{a}}{dt^n} \left(\frac{d}{c}\right)^n = 0. \quad (19)$$

390 The characteristic polynomial of this equation is
 391 obtained by considering as solution $a(t) = a_0 e^{\lambda t}$. We
 392 compute the relation

$$393 \quad -\frac{1}{2} + \sum_{n=1}^{\infty} \frac{1}{(n+2)!} \left(\frac{\lambda d}{c}\right)^n = 0, \quad (20)$$

394 which can be more elegantly written by using the
 395 Maclaurin series of the exponential function. If we
 396 redefine it by means of the variable $\mu = \lambda d/c$, we get

$$397 \quad -\frac{1}{2} + \frac{1}{\mu^2} \sum_{n=1}^{\infty} \frac{\mu^{n+2}}{(n+2)!}$$

$$398 \quad = -\frac{1}{2} + \frac{1}{\mu^2} \left(e^{\mu} - \frac{\mu^2}{2} - \mu - 1 \right) = 0. \quad (21)$$

399 The solutions to this equation can be obtained
 400 numerically. Apart from zero, the only purely real solu-
 401 tion can be nicely approximated as

$$402 \quad \lambda = \frac{9}{5} \frac{c}{d}, \quad (22)$$

403 which is a positive value. In summary, the rest state
 404 is not stable in the Lyapunov sense [29], and this
 405 implies that the particle can not be found at rest. In
 406 Fig. 2, a domain coloring representation of the func-
 407 tion $f(z) = z^2 + z + 1 - e^z$ is shown. The roots and the
 408 poles can be localized where all colors meet. The color
 409 represents the phase of the complex function. The shiny
 410 level curves represent the values for which $|f(z)|$ is an
 411 integer, while the dark stripes are the curves $\text{Re}f(z)$
 412 and $\text{Im}f(z)$ equal to a constant integer. The complex
 413 function $f(z)$ has an infinite set of zeros in the com-
 414 plex plane. All of them have a positive real part, while

415 all except two of them are complex conjugate numbers
 416 with a nonzero imaginary part. It can be analytically
 417 shown that, for zeros with a negative real part to exist,
 418 they have to be confined in a small region close to the
 419 origin. Consequently, numerical simulation is enough
 420 to confirm both the instability of rest and the existence
 421 of self-oscillations in the system.

422 As more generally stated below, everything is jig-
 423 gling because electromagnetic fluctuations are ampli-
 424 fied. Consequently, motion would be the essence of
 425 being and not rest, as could be inferred from the princi-
 426 ple of inertia in Newtonian mechanics. More precisely,
 427 and as we are about to show, it is uniform motion that it
 428 is unstable. This notion is precisely a strong suggestion
 429 in order to assume that inertia has an electromagnetic
 430 origin. But we shall give a more compelling one below.
 431 Be that as it may, the instability of stillness can be con-
 432 sidered, by far, the most fundamental finding of the
 433 present analysis.

5 Self-oscillations

434 We now proceed to show the existence of limit cycle
 435 oscillations of the particle. Since the rest state is unsta-
 436 ble and the speed of light can not be surpassed accord-
 437 ing to Eq. (14), the only possibilities left are uniform
 438 motion or some sort of oscillatory dynamics, whether
 439 regular or chaotic. In the first place, we rewrite Eq. (14)
 440 to a more amenable and familiar form. We have

$$441 \quad \frac{d^2}{c^2} a(t_r) + \frac{r}{c} \left(1 - \frac{v^2(t_r)}{c^2} \right)$$

$$442 \quad v(t_r) + \left(1 - \frac{v^2(t_r)}{c^2} \right) (x(t_r) - x(t)) = 0. \quad (23)$$

443 The main handicap of this equation is that it is
 444 expressed in terms of the retarded time $t_r = t - r/c$,
 445 which is the customary expression of the Liénard–
 446 Wiechert potentials. To obtain the same equation in
 447 terms of the present time t , we simply perform a time
 448 translation to the advanced time $t_a = t + r/c$. This
 449 allows to write

$$450 \quad a(t) + \frac{r}{d} \frac{c}{d} \left(1 - \frac{v^2(t)}{c^2} \right) v(t) + \left(\frac{c}{d} \right)^2$$

$$451 \quad \left(1 - \frac{v^2(t)}{c^2} \right) \left(x(t) - x \left(t + \frac{r}{c} \right) \right) = 0. \quad (24)$$

452 But now the problem is that this equation depends
 453 on the advanced time. In other words, Eq. (24) allows to
 454

Author Proof

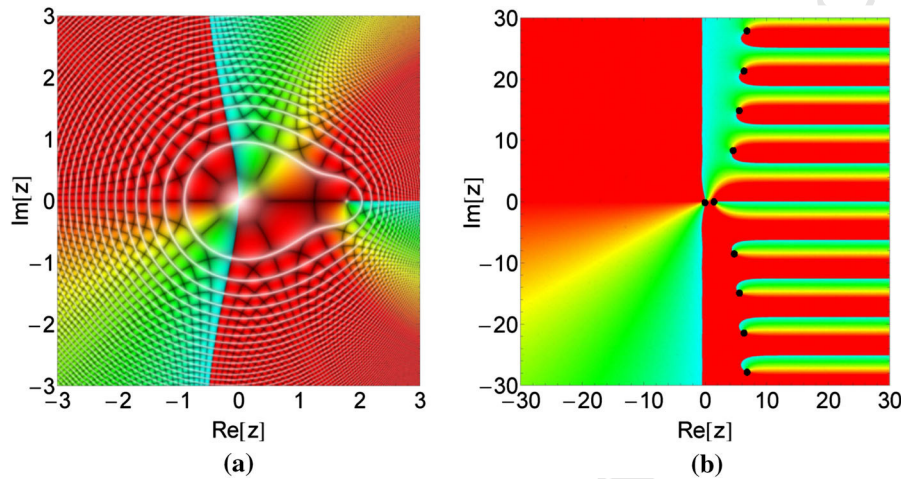


Fig. 2 The roots of the polynomial $f(z) = z^2 + z + 1 - e^z$ (a) domain coloring representation of the function $f(z)$. The roots and poles can be localized where all colors meet. In the present case, we clearly identify the roots $z = 0$ and $z = 9/5$. (b) Here

a zoom out of the function is shown (the coloring scheme has been simplified), with the distribution of zeros (black dots). As can be seen, all of them are distributed on the positive real part of the complex plane

455 derive the position and velocity at some time from the
 456 knowledge of such position and velocity in the past, by
 457 using the position in the future. This equation reminds
 458 of the equation of a self-oscillator [30]. Apart from the
 459 term of inertia and the linear oscillating term represent-
 460 ing the electromagnetic origin of Hooke's law [31,32],
 461 we have two nonlinear contributions. On the one hand,
 462 the second contribution on the left-hand side acts here
 463 as a damping term and it is responsible for the sys-
 464 tem's dissipation. This term is identical to other terms
 465 appearing in traditional self-oscillating systems, as for
 466 example the oscillator introduced by Lord Rayleigh's
 467 to describe the motion of a clarinet reed [33] and, to
 468 some extent, also to the Van der Pol's oscillator [34].
 469 On the other hand, the antidamping comes from the
 470 advanced potential. At first sight, in the limit of small
 471 velocities, the frequency of oscillation is $\omega_0 = c/d$,
 472 which allows to approximate the period as

$$473 \quad T = 4\pi \frac{r_e}{c}, \quad (25)$$

474 where $r_e = d/2$ is the radius of the electron. This
 475 equation gives a value of the period of approximately
 476 $T = 1.18 \times 10^{-22}$ s for the classical radius of the elec-
 477 tron. Therefore, the particle would oscillate very vio-
 478 lently, giving rise to an apparently stochastic kind of
 479 motion. This motion and the value of the frequency
 480 should not be unfamiliar to quantum mechanical theo-
 481 rists, since they can be related to the trembling motion

482 appearing in Dirac's equation [35], commonly known
 483 as *zitterbewegung*.

484 As we have shown in Sect. 2, the time-delay r
 485 depends on the kinematic variables. We insist that, in
 486 this sense, despite of the simplicity of the model at
 487 analysis, we are facing a terribly complicated dynamical
 488 system, since the delay itself depends on the speed
 489 and the acceleration of the particle. This kind of systems
 490 are formally referred in the literature as state-dependent
 491 delayed dynamical systems [36] and, from an analytical
 492 point of view, they are mostly intractable. Importantly,
 493 we note that for a system of particles, the dependence
 494 of the delay of a certain particle on the kinematic vari-
 495 ables of the others at several times in the past and the
 496 present as well, turn electrostatics into a nonlocal
 497 theory [37]. This functional dependence sheds some
 498 light into the significance of entanglement, which can
 499 now be regarded as a process of entrainment of nonlin-
 500 ear oscillators [38,39].

501 All this complexity notwithstanding, since we just
 502 aim at illustrating the existence of self-oscillatory
 503 dynamics, we shall have no problems concerning the
 504 integration of this system. According to Eq. (22), when
 505 the system is amplifying fluctuations from its rest state,
 506 we see that the rate at which the amplitude of fluctua-
 507 tions grows is comparable to the period of the oscil-
 508 lations. Therefore, averaging techniques, for exam-
 509 ple, the Krylov-Bogoliubov method, cannot be safely

510 applied in the present situation. More simply, we con-
 511 sider the differential equation (24) and write it in the
 512 phase space as

$$\begin{aligned} 513 \quad \dot{x} &= y, \\ 514 \quad \dot{y} &= -\frac{c}{d} \frac{r}{d} \left(1 - \frac{y^2}{c^2}\right) y - \left(\frac{c}{d}\right)^2 \left(1 - \frac{y^2}{c^2}\right) (x - x_\tau), \end{aligned} \quad (26)$$

516 where x_τ represents the position at the advanced time
 517 $t + \tau = t + r/c$. As we have shown in the previous
 518 section, the fixed point $\dot{x} = \dot{y} = 0$ is unstable. Apart
 519 from the rest state, asymptotically, there can be only
 520 two possibilities. Since the speed of light is unattain-
 521 able for massive particles, either the particle settles at
 522 a constant uniform motion at a slower speed, or its
 523 speed fluctuates around some specific value. We do not
 524 enter into the issue whether these asymptotic oscilla-
 525 tions are periodic, quasiperiodic, or chaotic. We shall
 526 just prove that uniform motion is not stable and, con-
 527 sequently, a self-oscillatory dynamics is the only pos-
 528 sibility, whatever its periodicity might be. Assume that
 529 uniform motion is possible at some speed y , which is
 530 a constant number βc . Then, we have that $x(t) = yt$
 531 and also that $x(t + r/c) = yt + yr/c$, which implies
 532 $x - x_\tau = -yr/c$. Substitution in Eq. (25) yields

$$\begin{aligned} 533 \quad \dot{x} &= y, \\ 534 \quad \dot{y} &= -\frac{c}{d} \frac{r}{d} \left(1 - \frac{y^2}{c^2}\right) y + \frac{c}{d} \frac{r}{d} \left(1 - \frac{y^2}{c^2}\right) y = 0. \end{aligned} \quad (27)$$

536 Thus, certainly, any uniform motion is also an invari-
 537 ant solution (a fixed trajectory, so to speak) of our state-
 538 dependent delayed dynamical system. However, it is
 539 immediate to show that this solution is unstable as well.
 540 We prove this assertion by computing the variational
 541 equation related to inertial observers

$$\begin{aligned} 542 \quad \delta \dot{x} &= \delta y, \\ 543 \quad \delta \dot{y} &= -\frac{c}{d} \frac{\delta r}{d} \left(1 - \frac{y^2}{c^2}\right) y - \frac{c}{d} \frac{r}{d} \left(1 - \frac{y^2}{c^2}\right) \delta y + \frac{c}{d} \frac{r}{d} \frac{2y^2}{c^2} \delta y - \\ 544 \quad & - \frac{c}{d} \frac{r}{d} \frac{2y^2}{c^2} \delta y - \left(\frac{c}{d}\right)^2 \left(1 - \frac{y^2}{c^2}\right) (\delta x - \delta x_\tau). \end{aligned} \quad (28)$$

546 At this point, we have to compute δr at $\dot{y} = 0$ and
 547 $y = \beta c$, with β a constant value. Using the formula
 548 (15), but evaluated at the present time, this calculation

can be carried out without difficulties yielding

$$\delta r(t) = \gamma^4 \beta \left(\frac{d}{c}\right)^2 \delta \dot{y}(t) + d \delta \gamma(t), \quad (29)$$

551 where again we notice that the variables are evaluated
 552 at the present time. Gathering terms and using the fact
 553 that $r = \gamma d$ for $\dot{y} = 0$, we finally arrive at the varia-
 554 tional problem

$$\begin{aligned} 555 \quad \delta \dot{x} &= \delta y, \\ 556 \quad \delta \dot{y} \gamma^2 &= -\frac{c}{d} \gamma \delta y - \left(\frac{c}{d}\right)^2 (1 - \beta^2) (\delta x - \delta x_\tau). \end{aligned} \quad (30)$$

558 If we consider solutions of the form $\delta x = Ae^{\lambda t}$, the
 559 characteristic polynomial of the system (30) is found.
 560 It reads

$$\lambda^2 \gamma^2 + \frac{c}{d} \gamma \lambda + \left(\frac{c}{d}\right)^2 (1 - \beta^2) (1 - e^{\lambda \gamma d/c}) = 0. \quad (31)$$

563 Two limiting situations appear. In the non-relativistic
 564 limit $\beta \rightarrow 0$ we can write

$$\lambda^2 + \frac{c}{d} \lambda + \left(\frac{c}{d}\right)^2 (1 - e^{\lambda d/c}) = 0. \quad (32)$$

566 which, considering $\mu = \lambda d/c$, can be written as

$$\mu^2 + \mu + 1 - e^\mu = 0. \quad (33)$$

568 This is in conformity with previous results [see Eq. (21)].
 569 Finally, in the relativistic limit, we get

$$\mu^2 + \mu + (1 - e^\mu)(1 - \beta^2) = 0, \quad (34)$$

571 where we have now defined $\mu = \lambda \gamma d/c$. Except for
 572 one eigenvalue, the real part of the solutions to this
 573 equation are always positive and therefore unstable for
 574 any value of β , as confirmed by numerical simulations
 575 (see Fig. 3). Again, an infinite set of frequencies are
 576 obtained, which can be written as

$$\omega_n = \eta_n \frac{c}{\gamma d}, \quad (35)$$

578 where the factor γ accounts for the time dilation related
 579 to Lorentz boosts. The parameters η_n , according to
 580 Fig. 3, can be reasonably approximated by means of
 581 a linear dependence on n , which is an integer greater or
 582 equal than one. From the same image, we can see that
 583 these parameters are almost independent of the speed
 584 of the system.

585 In this manner, we have proved the existence of
 586 self-oscillating motion in this dynamical system for

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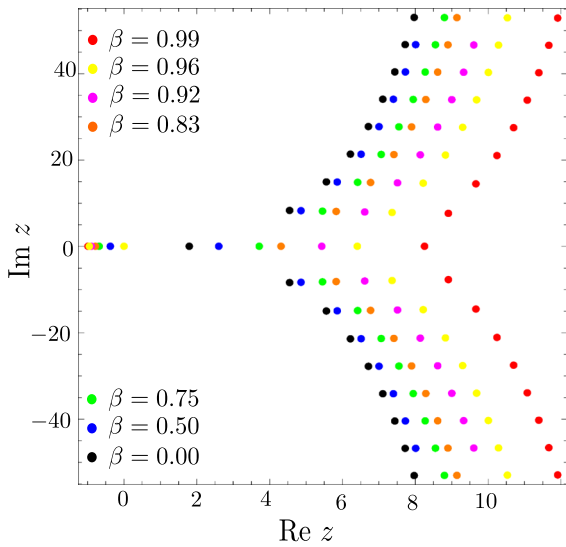


Fig. 3 The roots of the polynomial $f(z) = z^2 + z + (1 - e^z)(1 - \beta^2)$. The complex roots of the $f(z)$ have been numerically computed using Newton’s method for different values of the speed, ranging from the rest state ($\beta = 0$) to the ultrarelativistic limit. The values of the imaginary part depend weakly on β , and can be written as multiples of a fundamental frequency, what gives the spectrum of the self-oscillation $\omega_n \propto nc/\gamma d$

all values of β . We recall *en passant* that the damping term and the delay introduce an arrow of time in the system [40]. In other words, the limit cycle can be run in one time direction, but not in the reverse. This lack of reversibility is inherent to delayed systems, which depend on their previous history functions [41] and, therefore, are fundamentally non-conservative systems. Nevertheless, we note that the violation of energy conservation should only last a small time until the invariant limit set is obtained, and that it applies as long as we just look at the particle and not to the fields. This fact evokes nicely the time-energy uncertainty relations, as can be noticed in the next section. Even though self-oscillations were pointed out a long time ago for a charged particle [42], the instability of “classical” geodesic motion had been unnoticed before, perhaps due to the fact that artificial inertia was assumed and because there exists a dependence of the degree of instability on the geometry of the particle [43]. This would be simply natural, given the complexity of retarded fields, and justifies the use of the apparently simple present model.

6 The self-potential

In the present section, we obtain the relativistic expression of the potential energy of the charged body, starting again from the Liénard–Wiechert potential of the electromagnetic field. We denote this self-energy as U since it can be regarded as the non-dissipative energy required to assemble the system and set it at a certain dynamical state. As it will be clear at the end of the section, it harbors both the rest and the kinetic energy of the particle, and also a kinematic formulation of what we suggest might be the quantum potential, which is frequently written as Q in the literature [44].

The electrodynamic energy of the dumbbell can be computed as the energy required to settle it in a particular dynamical state. Since the magnetic fields do not perform work, we would have to compute the integral

$$U = \frac{e}{2} \int_{r_0}^r \mathbf{E} \cdot d\mathbf{r} = -\frac{e}{2} \int_{r_0}^r \nabla \varphi \cdot d\mathbf{r} - \frac{e}{2} \int_{r_0}^r \frac{\partial \mathbf{A}}{\partial t} \cdot d\mathbf{r}, \tag{36}$$

along some specific history describing a possible journey of the dumbbell. However, it can be shown that the second term is just the dissipative contribution. Therefore, we concentrate on the irrotational part of the field. The electrodynamic potential energy of the dumbbell is just given by the Liénard–Wiechert potential as

$$U = \frac{e^2}{16\pi\epsilon_0} \frac{1}{\mathbf{r} \cdot \mathbf{u}}, \tag{37}$$

where the additional one fourth factor comes from the fact that each charge brings a value $q = -e/2$. This can be written by means of Eq. (3) as

$$U = \frac{\hbar\alpha c}{4(r - l\beta)}. \tag{38}$$

If we now substitute Eqs. (15) and (16), and develop them in powers of d/c , we obtain the series expansion of the self-potential

$$U = \gamma \frac{\hbar\alpha c}{4d} - \gamma^7 \frac{a^2}{2c^2} \frac{\hbar\alpha}{4} \left(\frac{d}{c}\right) + \gamma^{13} \frac{3a^4}{8c^4} \frac{\hbar\alpha}{4} \left(\frac{d}{c}\right)^3 - \gamma^{19} \frac{5a^6}{16c^6} \frac{\hbar\alpha}{4} \left(\frac{d}{c}\right)^5 + \dots \tag{39}$$

We recall that these computations are very lengthy and again strongly recommend the use of software for symbolic computation. We arrive in this manner at the crucial point of this exposition. If we once again simply

Author Proof

647 assume the idea that inertia has an electromagnetic ori-
 648 gin, we can write the size of the particle as

$$649 \quad d = \frac{\hbar\alpha}{4m_e c}. \quad (40)$$

650 Substitution in the previous equation yields the series

$$651 \quad U = \gamma m_e c^2 - \frac{\hbar^2}{2m_e} \frac{\alpha^2}{8c^2} \gamma \left(\gamma^6 \frac{a^2}{2c^2} - \gamma^{12} \frac{3a^4}{8c^4} \left(\frac{d}{c} \right)^2 + \gamma^{18} \right. \\ 652 \quad \left. \frac{5a^6}{16c^6} \left(\frac{d}{c} \right)^4 - \dots \right), \quad (41)$$

653 which can be written more formally as

$$654 \quad U = \gamma m_e c^2 + \frac{\hbar^2}{2m_e} \frac{\alpha^2}{32r_e^2} \gamma \sum_{n=1}^{\infty} q_n (-1)^n \gamma^{6n} \frac{a^{2n}}{c^{2n}} \left(\frac{d}{c} \right)^{2n}, \quad (42)$$

656 where the coefficients $q_n = \{1/2, 3/8, 5/16, 35/128, 63/256 \dots\}$ of the expansion belong to a
 657 sequence, which can be computed from the quadrature
 658

$$659 \quad q_n = \int_0^1 \cos^{2n}(2\pi x) dx = \frac{(2n-1)!!}{2^n n!}. \quad (43)$$

660 We clearly identify two terms in Eq. (42). The first
 661 one is just the relativistic energy [45], which contains
 662 both the rest and the kinetic energy of the particle. But
 663 note that, in addition to the kinetic and the rest energy
 664 of the particle, the potential

$$665 \quad Q = \frac{\hbar^2}{2m_e} \frac{\alpha^2}{32r_e^2} \gamma \sum_{n=1}^{\infty} q_n (-1)^n \gamma^{6n} \frac{a^{2n}}{c^{2n}} \left(\frac{d}{c} \right)^{2n}, \quad (44)$$

666 has unveiled as a new contribution. By inserting the
 667 integral appearing in Eq. (43) into Eq. (44), we can
 668 derive, after summation of the series and one additional
 669 integration, the potential

$$670 \quad Q = -\frac{\hbar^2}{2m_e} \frac{\alpha^2}{32r_e^2} \gamma \left(1 - \frac{1}{\sqrt{1 + \gamma^6 \beta^2 \left(\frac{d}{c} \right)^2}} \right), \quad (45)$$

671 which vanishes for uniform motion. Again, we note
 672 how the Lorentz factor precludes traveling at speeds
 673 higher or equal than the speed of light.

674 This potential evokes nicely the quantum potential
 675 appearing in Bohmian mechanics [4,5], with the same
 676 term $\hbar^2/2m_e$ preceding it. Importantly, we notice the
 677 dependence of fluctuations on the fine structure con-
 678 stant. Moreover, we have found a dependence of this
 679 potential on the acceleration of the particle that, we
 680 should not forget, is evaluated at the retarded time. On
 681 the other hand, since

$$682 \quad Q = -\frac{\hbar^2}{2m_e} \frac{\nabla^2 R}{R}, \quad (46)$$

683 in quantum mechanics, we can settle a bridge between
 684 the square modulus of the wave function and the kine-
 685 matics of the particle in the non-relativistic limit. In
 686 this way, we would restore the old relationship between
 687 forces and geometrical magnitudes. Once the dynam-
 688 ics is constrained to the asymptotic limit cycle, a rela-
 689 tion between the acceleration of the particle and its
 690 position can be established and replaced in Q . Then,
 691 the resulting partial differential equation is similar to
 692 Helmholtz's equation

$$693 \quad \nabla^2 R + \frac{2m_e}{\hbar^2} QR = 0, \quad (47)$$

694 while we can independently write down the Hamilton-
 695 Jacobi equation for a particle immersed in an external
 696 potential $V(x, t)$. In the non-relativistic limit, it is given
 697 by

$$698 \quad \frac{\partial S}{\partial t} + \frac{1}{2m_e} (\nabla S)^2 + Q + V = 0. \quad (48)$$

699 In principle, once the two previous Eqs. (47) and (48)
 700 have been solved using the knowledge of the trajectory
 701 of the particle, the wave function can be built as

$$702 \quad \psi(x, t) = R(x, t) \exp\left(\frac{i}{\hbar} S(x, t)\right), \quad (49)$$

703 even though this solution may not be easily attained
 704 in most cases, especially when an external potential
 705 is present. Interestingly, we can see from these rela-
 706 tions that the wave function is a real objective field,
 707 as claimed in the seminal works of David Bohm [4,5],
 708 and not just a probabilistic entity. Both its modulus
 709 and phase are related to internal and external electro-
 710 dynamic forces.

711 To gain some insight into the self-potential of the
 712 "free" particle, we illustrate these ideas using an exam-
 713 ple. For this purpose, we can invoke the oscillatory
 714 dynamics after the transient amplification to show the
 715 repulsive nature of electrodynamic fluctuations. A con-
 716 servative version of the potential $Q_c(x)$ can be derived,
 717 which should only be regarded as an illustrative approx-
 718 imation. If we disregard the delay and consider the
 719 approximation $a = -\omega_0^2 x$, in the non-relativistic limit,
 720 and keeping just the two first term of the series, we
 721 obtain the potential

$$722 \quad Q_c(x) = -\frac{\hbar^2}{2m_e} \frac{\alpha^2}{64r_e^2} \left(\frac{1}{d^2} x^2 - \frac{3}{4d^4} x^4 \right). \quad (50)$$

723 This potential is very well known in the world
 724 of nonlinear dynamical systems since it appears in

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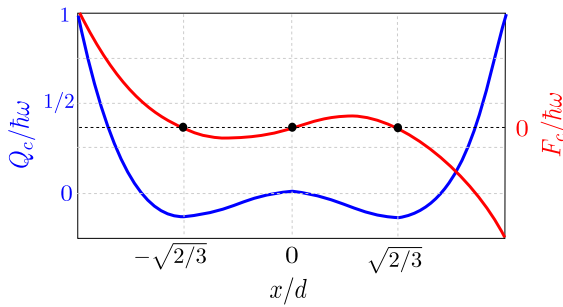


Fig. 4 The quantum potential $Q_c(x)$. This conservative approximation of the repulsive potential (blue line) has an unstable fixed point at the origin $x^* = 0$, flanked by two minima, representing stable fixed points at $x^* = \pm\sqrt{2/3}$. The repulsive character of this potential guarantees the perpetual oscillatory motion of electrodynamic bodies. An approximation of the self-force is shown in red

the Duffing oscillator [46]. This oscillator has been a paradigmatic model in the study of chaotic dynamical systems and has received remarkable attention both in physics and engineering, since it can describe many important phenomena, such as beam buckling, superconducting Josephson parametric amplifiers, or ionization waves in plasmas, among many others. It illustrates in a very clear manner the instability of stillness (see Fig. 4), because $Q_c(x)$ presents a maximum at $x = 0$. In particular, this potential is responsible for the spontaneous symmetry breaking of the Poincaré group. We recall that symmetry breaking is a typical feature of nonlinear dynamical systems [47–49].

Interestingly, this potential can be written in a simplified form as

$$Q_c(x) = -\frac{1}{2}\hbar\omega \left(\frac{1}{2d^2}x^2 - \frac{3}{8d^4}x^4 \right), \quad (51)$$

where the frequency $\omega = \alpha c/2d$ has been defined, which is manifestly related to the frequency of *zitterbewegung* of the dumbbell.

What we find of the greatest interest in this expression is that it nicely evokes Planck’s relation. Moreover, we recall that m_e is proportional to \hbar , as long as we are in a position to assume that mass is of electromagnetic origin. Therefore, all sorts of energy and momentum can be ultimately written as proportional to Planck’s constant. For example, the rest energy of the electron is written as $\hbar\omega/2$. It is then reasonable to argue that photons, which are light pulses emitted from accelerated electron transitions between different energy states, have energy $E = \hbar\omega$. Furthermore, by considering the relativistic relation $E = pc$, it is immediate to obtain

from this equality that $p = \hbar k$, which brings in the De Broglie’s relation between momentum and wavelength.

As we can see, perhaps the main problem when studying the electrodynamics of extended bodies is that it leads to very complicated state-dependent delayed differential equations. Things would get terribly complicated if continuous bodies are considered, instead of the simple toy discrete model used here [43]. This physical phenomenon arises as a consequence of the principle of causality, which imposes a limited speed at which information can travel in physics, introducing an infinite number of degrees of freedom in the nonlinear Lagrange equations. In fact, we wonder how the principle of least action can be reformulated to cover the complex time-delayed systems appearing in electrodynamics. In light of these facts, and from a practical point of view, the Schrödinger equation would be surely a much more appropriate and manageable mathematical framework than the use of the complicated functional differential equations resulting from the Liénard–Wiechert potentials to treat quantum problems. Certainly, it would not be surprising that partial differential equations, which have an infinite number of degrees of freedom, are of so much usefulness replacing delayed systems, which harbor an infinite number of degrees of freedom as well.

7 Discussion

As we have shown, the dynamics of an extended charged moving body has resemblances with the dynamics of the silicon droplets experimentally found in the recent years. However, in our picture, the waves travelling with the particle “belong” to the particle itself, and do not require of any medium of propagation (any aether), since they are of electromagnetic origin. In our model, the fluctuations arise as self-interactions of the particle with its own field and have as an analogy the fluctuating platform appearing in their experiments [7]. Nevertheless, this analogy must be drawn with great care, since the physical phenomenon leading to fluctuations in our moving charged body is not resonance, but self-oscillation [30].

The most astonishing consequence of the present work is the demonstration of the possibility of an instability of natural or uniform motion, which defies common intuition and beliefs on radiation as a purely damping field on electromagnetic extended moving sources.

Author Proof

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We believe that this misunderstanding is present at the beginning of many important introductory texts on quantum theory to justify the imperious necessity of a quantum mechanical theory that has no basis on the classical world [50]. On the contrary, the present work suggests that self-interactions provide the required repulsive force (the quantum force) to avoid the collapse of electro-dynamical systems. In particular, we predict that self-interactions and recoil forces are enough to stabilize the hydrogen atom and prevent its collapse [51].

We also note that the wave-particle duality is immediately solved in our framework. The waves are just perturbations of the fields, and any charged accelerated particle can present such perturbations as a consequence of its self-oscillatory dynamics. Furthermore, there does not exist a fundamental particle that does not participate from some fundamental interaction and, consequently, there can be a pilot-wave [52] attached to any charged particle in accelerated motion. Importantly, we highlight the rich dynamical feedback interaction between these two apparently differentiated entities. We recall that feedback is a crucial phenomenon for the understanding of nonlinear dynamical systems in general, chaotic dynamics, and, especially, for control theory [53].

It is now evident that nothing can travel faster than field perturbations since, any aggregate of charge, whatever its nature is, will show resistance to acceleration due to its electromagnetic energy. This intuition brings back the concept of *vis insita*, as appearing in Newton's work [6]. A concept that is also related to the original notion of inertia and Galileo's *resistenza interna* [54], and which can be traced back to the seminal works of the Dominican friar Domingo de Soto [55,56]. The fact that the inertia of a body might be of electromagnetic origin (electroweak and strong, if desired) is an old argument in physical theories. As we have shown, it has been a sufficient and necessary condition to derive Newton's second law, kinetic energy, Einstein's mass-energy relation and what seems to be the quantum potential, just from Maxwell's electro-dynamics. In this way, the present work gives a foundation of classical and quantum mechanics in the theory of electro-dynamics [57].

Perhaps, the greatest lesson of Einstein's relation is not that energy is mass, but that mass is a useful and simple way to gather the constants appearing in electrostatic energy. Consequently, we shall not invoke

Occam's razor to defend the idea of gravitational mass as a redundant concept in fundamental physics. Instead, we focus the attention on the fact that our findings imply to reconsider Newton's second law as a law of statics, just as suggested by D'Alembert. Following the same line of reasoning, this idea perfectly connects with the theory of general relativity, since the principle of equivalence simply states that, in a non-inertial reference frame comoving with a body, any object experiences forces of inertia. In fact, these forces are equivalent to a gravitational field. Therefore, an electromagnetic theory of the gravitational field would also be in accordance with the principle of equivalence. Moreover, the identity of inertial and gravitational mass would be the consequence of a very simple fact, *i.e.*, their common electromagnetic origin. However, we must be careful at this point, since electromagnetic forces create strong ripples in space-time. Thus, a freely falling extended charged particle in a gravitational field, which in general relativity would correspond to an inertial observer, can experience very strong tidal self-forces that, as we have shown, can lead to self-oscillations.

Delving deeper into the principle of covariance, we recall that the electromagnetic stress-energy tensor can be plugged into Einstein's equation and interpreted as a curvature of spacetime. The Einstein-Maxwell equations are nonlinear high-dimensional partial differential equations, which can have as solutions solitary waves [58,59]. Certainly, the model presented in this work is far too simplistic and unrealistic, because it assumes a rigid solid as a particle, which is contrary to electromagnetic theory, and whose structure is unstable. We expect particles to rotate and also to be deformable, and wonder if these two properties should be enough to stabilize the electron.

To conclude, we must not miss the chance for self-criticism. Firstly, the simplicity of the model should prevent us from drawing too general conclusions. It can be shown that purely longitudinal motion of the dumbbell is dissipative. The authors recognize to have found a dependence of instability on the geometry of an electrodynamic moving body [43]. As the shape of the body turns from oblate to prolate, a Hopf bifurcation befalls. Therefore, some external field perturbations might be necessary to unleash the oscillation for more complicated bodies. Secondly, a full correspondence between electro-dynamics and the relativistic formalism of quantum mechanics has not been here provided. Nevertheless, we hope that this new perspective,

based on modern theories of nonlinear dynamics, might serve to enlighten the complex dynamics of elementary classical particles and, if not, at least to drive physics closer to the establishment of a dynamical picture of fundamental particles.

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Compliance with ethical standards

Conflicts of interest The authors declare that they have no conflict of interest

Appendix

The following lines are devoted to obtain a power series relating the size of the particle d and the magnitude of the delay r/c . This relation allows us to approximate the distance l between the dumbbell’s position at time t and at the delayed time t_r , as a function of the mass center velocity, its derivatives and the particle’s size [20,21]. We begin with the relation

$$d = r\sqrt{1 - \left(\frac{l}{r}\right)^2} = r\left(1 - \frac{z^2}{2} - \frac{z^4}{8} - \dots\right), \quad (52)$$

where the variable $z = l/r$ has been introduced. On the other hand, Eq. (6) can be rewritten as

$$z = \frac{l}{r} = \beta + \frac{a}{2c^2}r + \frac{\dot{a}}{6c^3}r^2 + \frac{\ddot{a}}{12c^4}r^3 + \frac{\dddot{a}}{120c^5}r^4 \quad (53)$$

The square of z can then be computed. If we disregard the terms of the third order and higher orders as well, we obtain

$$z^2 = \beta^2 + \frac{a}{c^2}\beta r + \frac{a^2}{4c^4}r^2 + \frac{\dot{a}}{3c^3}\beta r^2 + O(r^3). \quad (54)$$

Concerning the fourth power of z we can write

$$z^4 = \beta^4 + \frac{2a}{c^2}\beta^3 r + \frac{3a^2}{c^4}\beta^2 r^2 + \frac{2\dot{a}}{3c^3}\beta^3 r^2 + O(r^3). \quad (55)$$

to the same approximation as before.

Substitution of Eqs. (54) and (55) into Eq. (52), after gathering terms, yields

$$d = \left(1 - \frac{\beta^2}{2} - \frac{\beta^4}{8}\right)r - \frac{a}{2c^2}\beta\left(1 + \frac{\beta^2}{2}\right)r^2 - \left(\frac{a^2}{8c^4}\left(1 + \frac{3\beta^2}{2}\right) + \frac{\dot{a}\beta}{6c^3}\left(1 + \frac{\beta^2}{2}\right)\right)r^3 + O(r^4). \quad (56)$$

If we consider the non-relativistic limit, by just keeping terms of the first order in β , we arrive at the approximated relation

$$d = r - \frac{a}{2c^2}\beta r^2 - \left(\frac{a^2}{8c^4} + \frac{\dot{a}}{6c^3}\beta\right)r^3. \quad (57)$$

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